

Conditional Retrospective Voting in Large Elections

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Two distinct approaches to modeling voting behavior

- economics literature
- ▷ portrays voters as sophisticated individuals
 - ▷ well-defined preferences
 - ▷ solve complicated signal-extraction problems
 - ▷ have correct expectations, even about counterfactuals

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We offer an **equilibrium model of retrospective voting**
(see also Bendor, Diermeier, Kumar, Siegel, and Ting for a non-equilibrium, adaptive model of voting behavior)

Retrospective voting: Example

Suppose voter knows $u(B) = 1$ but needs to learn A 's performance.

time	signal	vote	election outcome	observed payoff
1	a	A	A	0
2	a	B	A	2
3	a	A	B	1
4	b	B	A	0
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Voting behavior at $t = 8$ after observing signal a :

$$\frac{0 + 2 + 2}{3} > 1 = u(B) \Rightarrow \text{vote for } A$$

Novel feature: Sample selection bias

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Retrospective voting + private information \Rightarrow biased learning + voting

Our contributions in this paper

- Propose a new equilibrium concept to capture **retrospective voting** with **private information** under a **large electorate**
 - formally capture biased learning
- Explore the **implications** of retrospective voting

Standard voting environment

- Election: 2 alternatives (e.g., parties) A and B
- State of the world $\omega \in \Omega = [-1, 1]$, distribution G
- Continuum of players
 - observe conditionally i.i.d. private signals \mathbb{S} with precision $q(\cdot | \omega)$
 - simultaneous voting
- Election outcome: A elected iff vote share of $A \geq \rho \in (0, 1)$
- Payoffs $u(A, \omega) \uparrow$ in ω , $u(B, \omega) \downarrow$ in ω
- In the paper, we allow for heterogeneous info/preferences
- Assumptions: monotone utility + MLRP + technical

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$$v(s; c) = E(u(A, \omega) | W \geq c, S = s) - E(u(B, \omega) | W < c, S = s)$$

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Definition

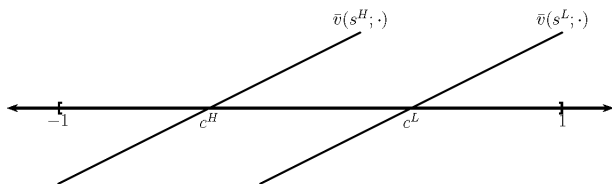
A retrospective voting equilibrium is a strategy σ^* and an election cutoff c^* such that (i) σ^* is optimal given c^* , and (ii) c^* is an election cutoff given σ^* .

Example

- $\omega \sim U[-1, 1]$
- $u(A, \omega) = \omega$, $u(B, \omega) = -\omega$, so first-best cutoff is $c^{FB} = 0$
- Binary signals $\{s^L, s^H\}$
 - precision $q(s^H | \omega) = .5 + r\omega$, where $r \in (0, .5]$

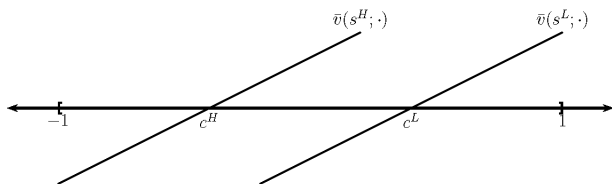
Finding an equilibrium

Step 1. Compute difference in expectations $v(s^L; c)$ and $v(s^H; c)$



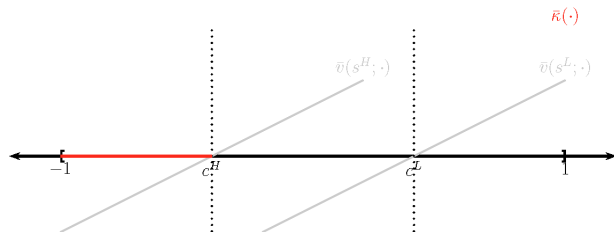
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Step 2. Find “personal cutoffs” c^H and c^L that make voters indifferent, i.e., $v(s^j; c^j) = 0$, $j = L, H$.



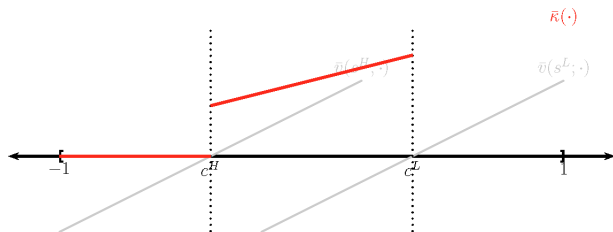
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Step 3. Compute share voting for A for each possible election cutoff: $\bar{\kappa}$



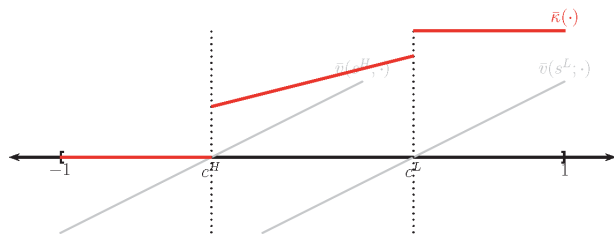
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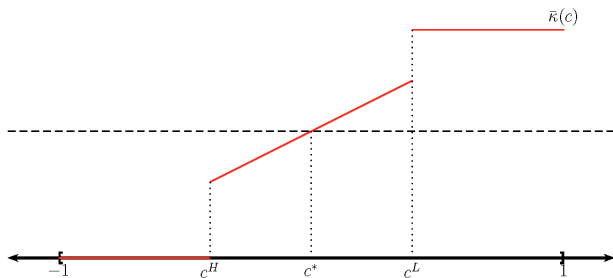
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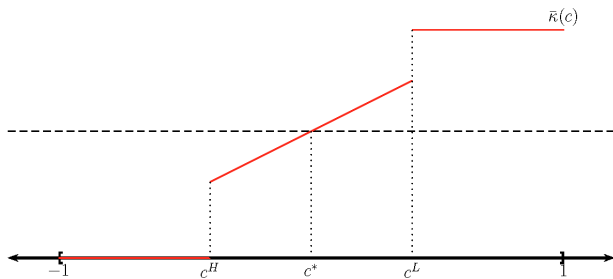


Finding an equilibrium

Step 4. Intersect vote-share for A with electoral rule to find equilibrium cutoff c^*



Compare to Nash eqm & sincere voting



Implications of retrospective voting derived in the paper

- Information not efficiently aggregated in general
 - Most attractive alternative occasionally chosen in wrong states
 - But there is a limit to how bad elections can perform
 - Information precision and electoral rules matter
 - But not always the case that more info improves welfare
- Value of risky alternative is overestimated
 - Justifies conservatism; supermajority rules
- Cannot infer party quality from observed performance
 - Elections might be very valuable even if parties are observed to perform similarly
- Composition effects: partisanship depends on own+others' preferences
 - Voting in local vs national elections can be different
- Political competition: parties have incentives to polarize
 - Polarization can increase welfare